

# KUNAL PRATAP SINGH

[Google Scholar](#) | Email : [ksingh@ee.iitr.ac.in](mailto:ksingh@ee.iitr.ac.in) | [Webpage](#)

## RESEARCH INTERESTS

Perception for Robotics; Efficient Neural Networks; Active Visual Learning; Lifelong Learning

## EDUCATION

**Indian Institute of Technology, Roorkee**

2016-2020

*Bachelor of Technology*, Department of Electrical Engineering

Advisor: Prof. G.N. Pillai

## PUBLICATIONS

MOCA: A Modular Object-Centric Approach for Interactive Instruction Following. [\[pdf\]](#)[\[code\]](#)

**Kunal Pratap Singh\***, Suvaansh Bhambri\*, Byeonghwi Kim\*, Roozbeh Mottaghi, Jonghyun Choi  
arxiv preprint, 2020

Learning Architectures for Binary Networks. [\[pdf\]](#)[\[code\]](#)

**Kunal Pratap Singh\***, Dahyun Kim\*, Jonghyun Choi

*European Conference on Computer Vision (ECCV)*, 2020

Extended version under submission in *IEEE T-PAMI*

Improving Mask Prediction for Long Horizon Instruction Following. [\[pdf\]](#)

**Kunal Pratap Singh\***, Suvaansh Bhambri\*, Byeonghwi Kim\*, Jonghyun Choi

*Embodied Vision, Actions & Language (EVAL) Workshop*

*European Conference on Computer Vision (ECCV)*, 2020

A Fast, Scalable and Reliable Deghosting Method for Extreme Exposure Fusion. [\[pdf\]](#)[\[code\]](#)

K. Ram Prabhakar\*, Rajat Arora\*, Adhitya Swaminathan, **Kunal Pratap Singh**, and R. Venkatesh Babu

*International Conference on Computational Photography (ICCP)*, 2019

## RESEARCH EXPERIENCE

**GIST Computer Vision Lab**

*Research Assistant*

**Gwangju Institute of Science and Technology, South Korea**

May 2020-Present

Advisors: [Dr. Jonghyun Choi](#), [Dr. Roozbeh Mottaghi](#) (Research Manager, Allen Institute for AI)

- Worked on the task of embodied instruction following on the ALFRED benchmark.
- Proposed a modular agent that decouples the policy and perception aspects of the problem.
  - Proposed an object-centric mask prediction mechanism for accurate object interaction.
  - Leveraged language based dynamic filters for cross-modal reasoning and generalization.
  - Proposed an obstacle avoidance mechanism to facilitate smooth navigation through the environment.
- Our proposed approach achieves the best performance (till date) on the test leaderboard [here](#).
- Work under review at **CVPR 2021**. Runners up on the ALFRED challenge in **ECCV 2020** workshop with latent version of this work.

**GIST Computer Vision Lab**

*Research Intern*

**Gwangju Institute of Science and Technology, South Korea**

May 2019-Nov 2019

Advisor: [Dr. Jonghyun Choi](#)

- Led a collaborative effort to develop the first architecture search method for binary neural networks.
- Developed a gradient based architecture search approach to search architectures with binary parameters constraints.
  - Proposed a new cell template and search space to accomplish this.
  - Added a diversity-based objective to ensure exploration in early stages of the search.
  - Redefined the utility of zeroise layer for searching sparser architectures.
- Our method (BNAS) led to superior performing backbone architectures for binary networks.
- Work published in **ECCV 2020**, extended version under review in T-PAMI.

**Video Analytics Lab, Department of CDS**

*Research Intern*

**Indian Institute of Science, India**

Nov 2018 to Jan 2019

Advisor: [Dr. R. Venkatesh Babu](#)

- Worked on developing a fast and scalable method for artifact free exposure fusion that can any number of images as input.
- Additionally, prepared a dataset of 582 varying exposure images with corresponding deghosted HDR images to train our model
- Developed method achieved a speed-up of around 54x over existing state-of-the-art HDR fusion methods.
- Project led to publication in **ICCP 2019**.

- Worked on the visual perception module of an autonomous vehicle as a part of the Mahindra Autonomous Vehicle Challenge.
- Used real time collected data to design lane detection and speed bump detection systems using OpenCV.
- Implemented a self-similarity model using a fixed template for identifying speed bumps and zebra crossing in the path.

## TALKS

---

- Embodied Vision, Actions and Language Workshop ([EVAL](#)), ECCV 2020.
- Invited talk on How to get started in Research. Organized by Student Mentorship Program, IIT Roorkee. [\[slides\]](#)

## AWARDS

---

- Bronze Prize, Samsung Humantech Awards,2020 (for ECCV work on binary neural networks).
- Awarded the National Talent Search Examination (NTSE) Scholarship for high school and undergraduate studies.
- Awarded the Kishore Vaigyanik Protsahan Yojana (KVPY) Fellowship, which included a fully-funded opportunity to pursue a basic sciences degree from the Indian Institute of Science (IISc), Bangalore, India.

## TECHNICAL SKILLS

---

- Languages and Toolkits: Python, Pytorch, Tensorflow, C++, Docker, Git

## REFERENCES

---

### **Jonghyun Choi**

Assistant Professor

School of EECS / Graduate School of AI

Computer Vision Lab

GIST (Gwangju Institute of Science and Technology)

Contact : [jhc@gist.ac.kr](mailto:jhc@gist.ac.kr)

### **Roozbeh Mottaghi**

Research Manager

PRIOR Team, Allen Institute for AI

Affiliate Associate Professor

Paul G. Allen School of Computer Science & Engineering

University of Washington

Contact : [roozbehm@allenai.org](mailto:roozbehm@allenai.org)

### **G. N. Pillai**

Professor / Head of Department

Department of Electrical Engineering

Indian Institute of Technology, Roorkee

Contact : [gnathfee@iitr.ac.in](mailto:gnathfee@iitr.ac.in)